

SIGGRAPH2012

The 39th International Conference and Exhibition on Computer Graphics and Interactive Techniques

Beyond Programmable Shading Course
ACM SIGGRAPH 2012

Dynamic Sparse Voxel Octrees For Next-Gen Real-Time Rendering

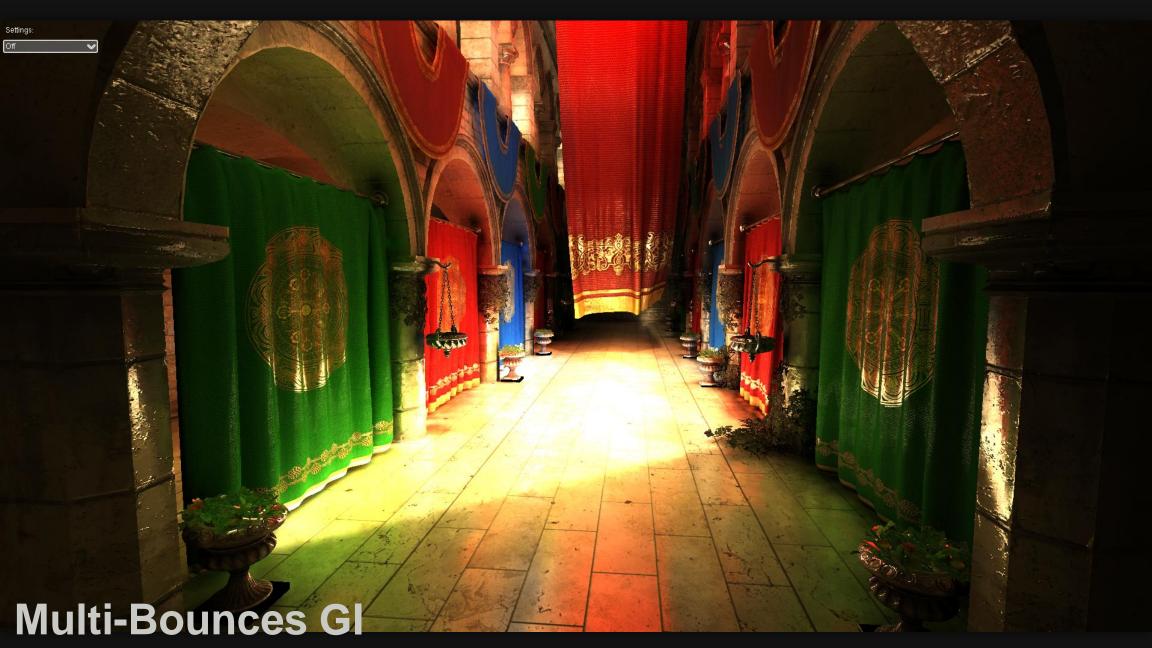
Cyril Crassin,
NVIDIA Research









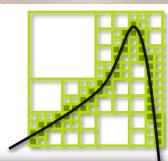


Sparse Voxel Octree

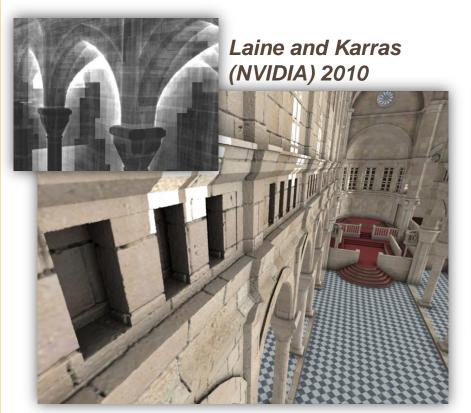
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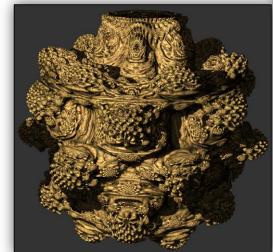
Compact multi-resolution voxel representation



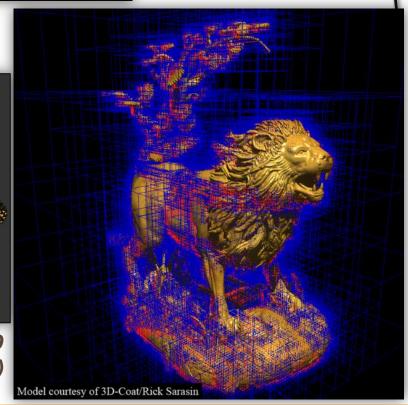


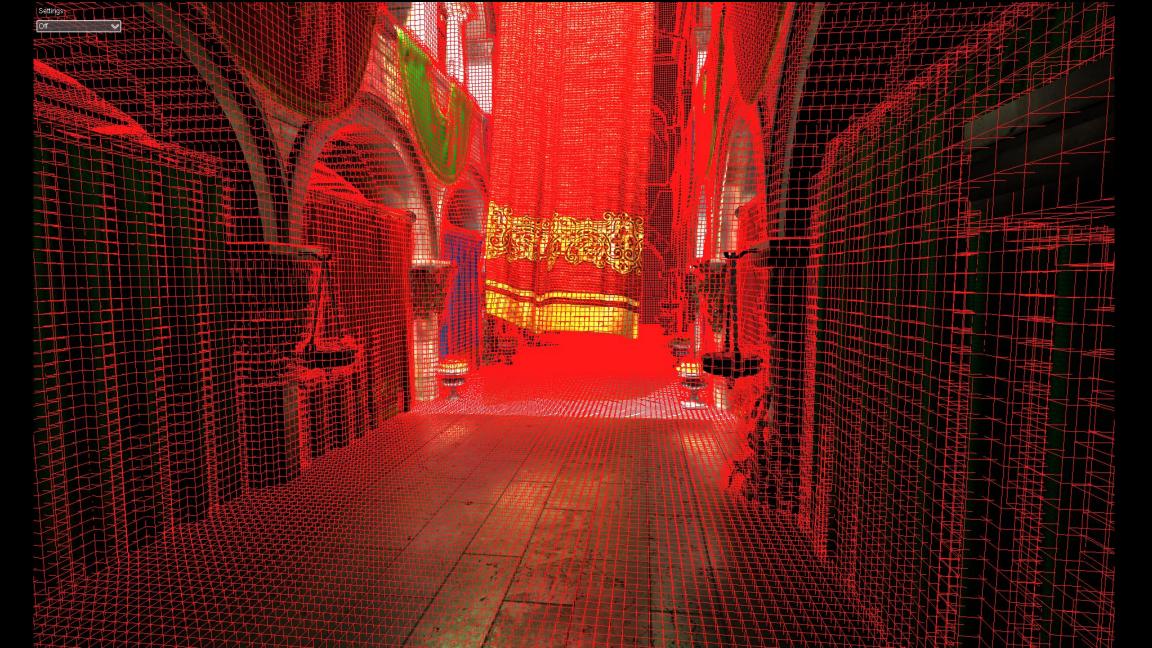
Olick. 2008





Crassin et al. 2009 (GigaVoxels)

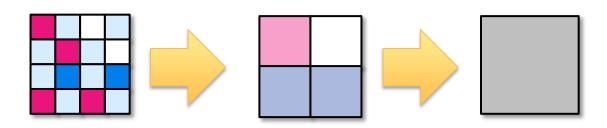


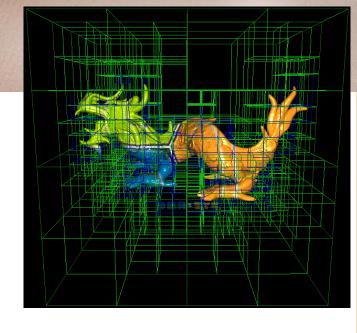


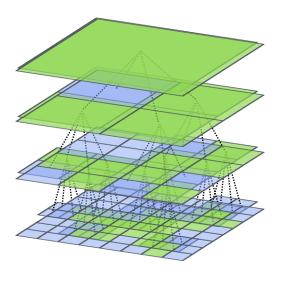
Voxel Octree

Hierarchical volumes

- Multi-resolution geometry
- Filtered values



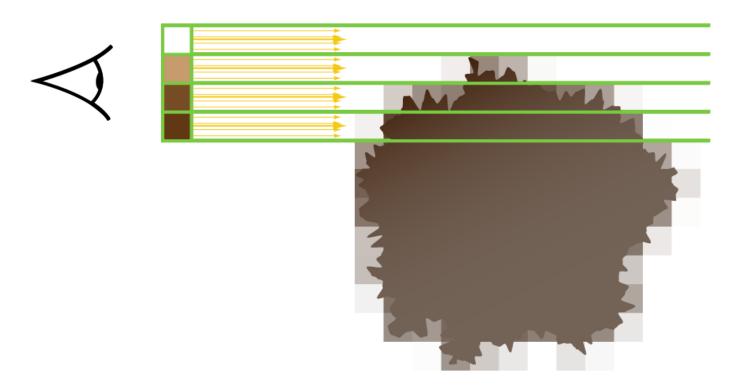




Geometry pre-filtering

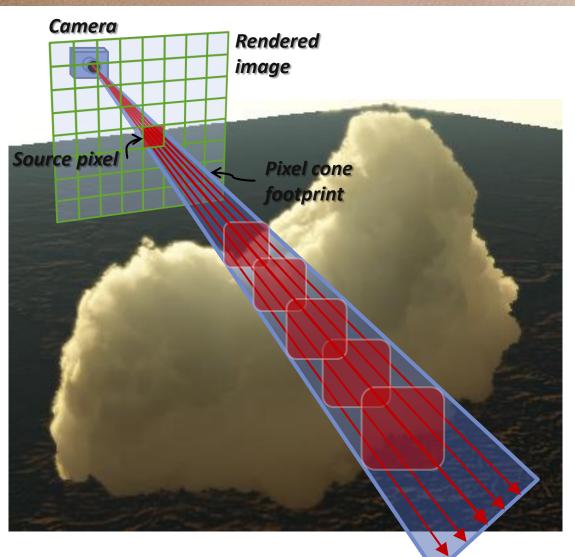


- Pre-filtered geometric representation
 - Adapt geometry-resolution to sampling resolution



Voxel cone-tracing model

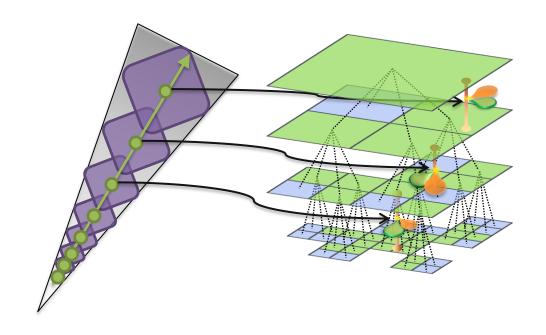




Voxel cone-tracing model



- Filtered geometry is integrated as a participating media
 - Volume ray-casting



Challenges



Representation

Global scene access

Filtering

#1 : Cinematic image quality

- Aliasing, Depth Of Field, Geometry Complexity
- Transparency

#2: Illumination

Visibility and light transport

#4: Production costs

 Content creation, Procedural amplification /Generation, LODs

#5 : Scaling up

Massive detailed scenes

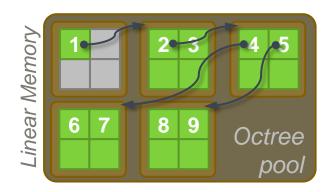
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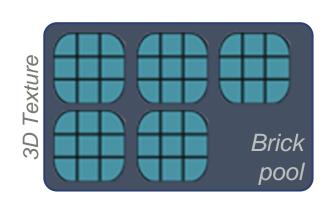
SVO STORAGE AND TRAVERSAL



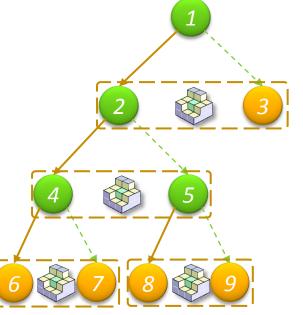
SVO Structure

- Nodes in linear video memory
 - 2x2x2 nodes tiles
 - 1 pointer per node to a node-tile
- Voxels stored into a 3D texture
 - Allows hardware tri-linear interpolation



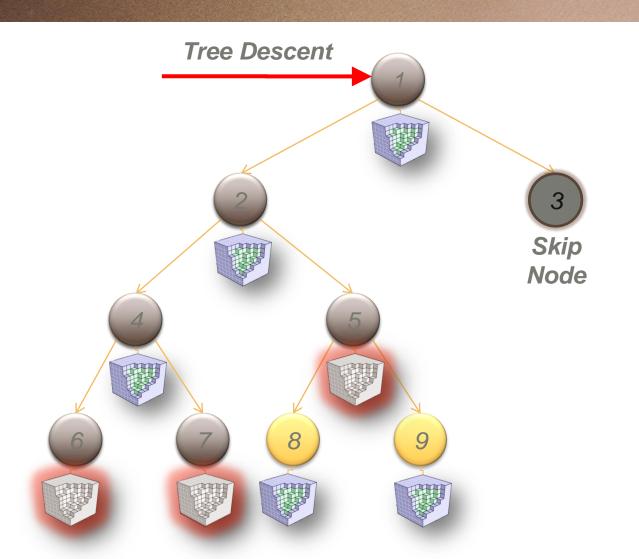


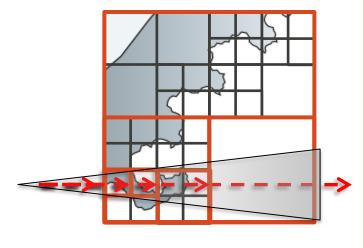




Octree traversal







One thread/cone

- KD-restart
 - Dependent accesses
- Stack-based
 - Local thread storage

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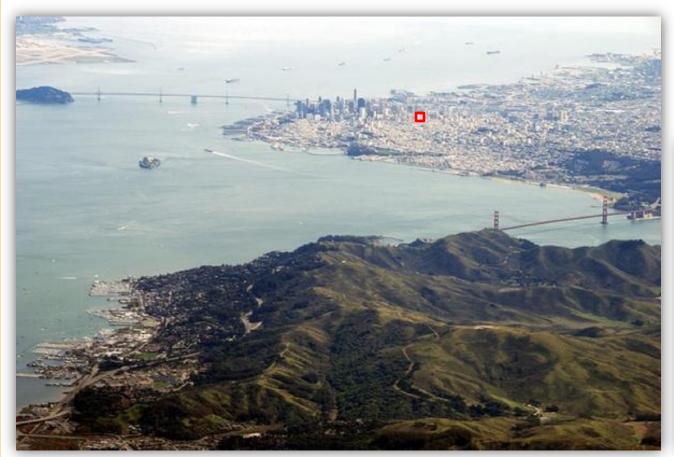
Challenge #1

CINEMATIC IMAGE QUALITY



Massive detailed scenes







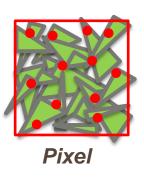
Pixel



Per-pixel integration (AA)



- Supersampling / MSAA not scalable
 - Will always be beaten by geometry



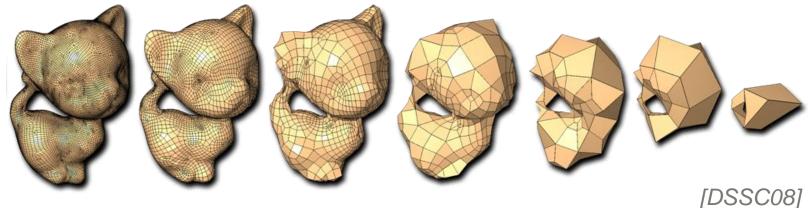
- Per-primitive transform + raster
 - For mostly averaged geometries

Pre-filtering



- Pre-filtering geometry is the only-way to go!
 - Adapt geometry-complexity to sampling resolution

But B-reps don't filter correctly ⊗



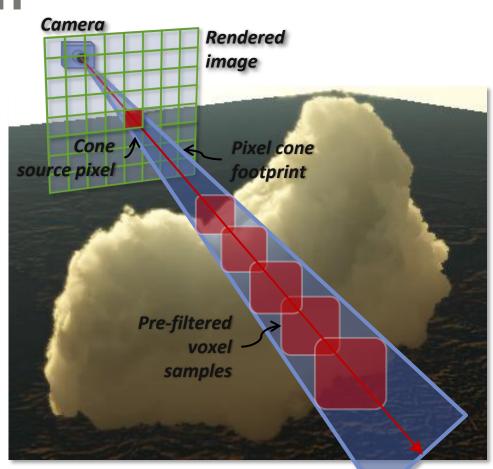
Voxel LOD



Scalable representation

- Unique rep + multi-scale
- Continuous LOD

- Very high voxel resolution ⊗
 - Animation difficult



Forest rendering



- One 3D texture/tree [Bruneton et al. 2012]
 - See PROLAND : http://proland.inrialpes.fr
- 51FPS @1024x768, 180,000 trees. GTX 580
- Trees only: 10.6ms



Voxel depth-of-field



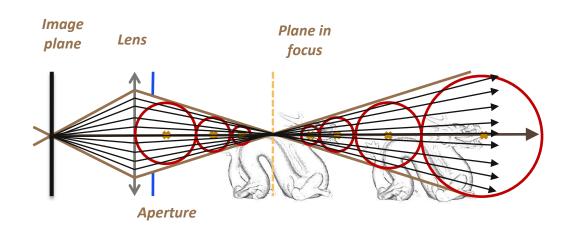








The blurrier, the faster!



Correlation problem

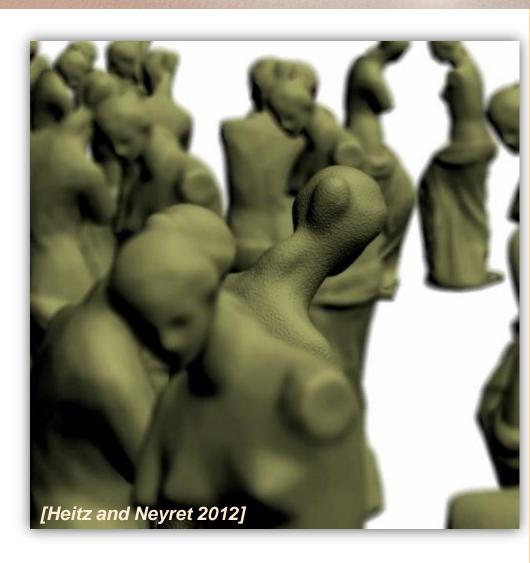


Representing Appearance And Pre-Filtering Subpixel Data In SVOs

[Heitz and Neyret 2012]



- 3-10Mcones/s
 - 100-300ms / frame@720p (1280x720)



Limitations



- Primary rays require massive voxel resolutions
 - Require out-of-core rendering

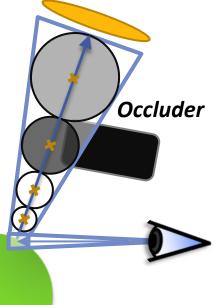
- Animation is difficult
 - Highly tessellated object in one voxel

Voxel soft shadows

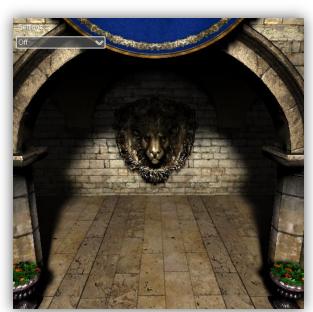
One cone per pixel

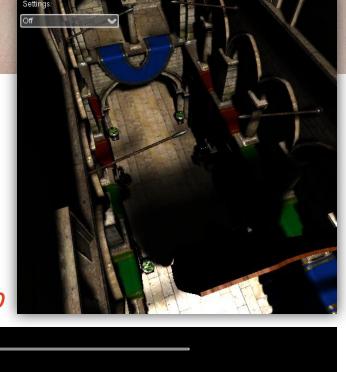
The smoother, the faster to compute!

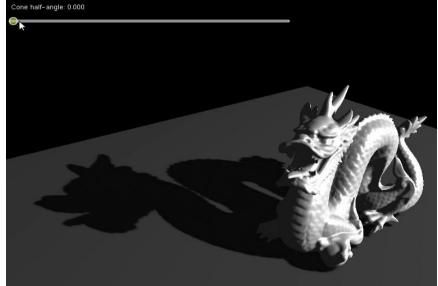








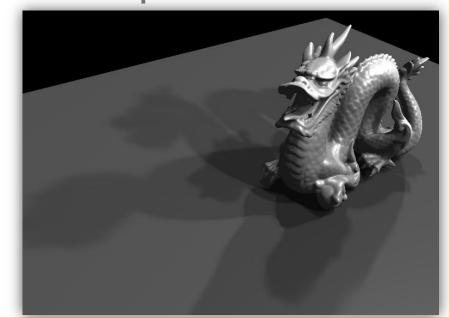




Voxel soft shadows



- Multiple shadowing lights sources
 - Only one geometry pass
 - Scales much better than shadow maps!

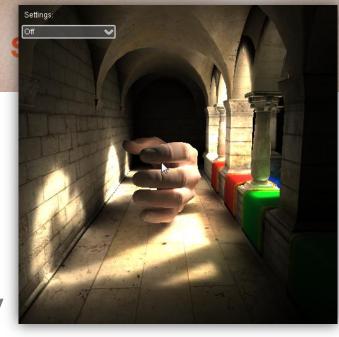


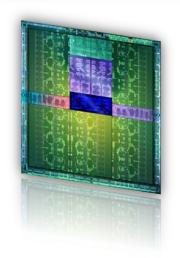


Rendering pipeline

- Hybrid rendering pipeline
 - Rasterized primary rays
 - GPU pipeline optimized for direct visibility
 - Cone-traced secondary rays
 - Flexibility and scalability





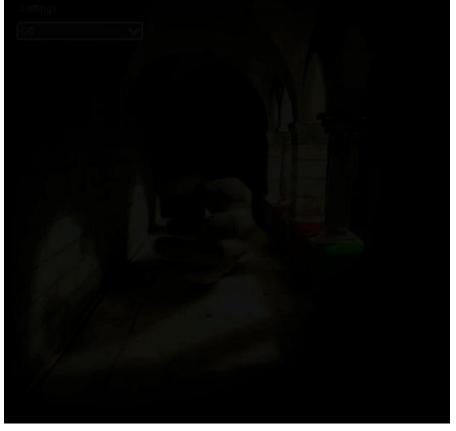


GIVoxels



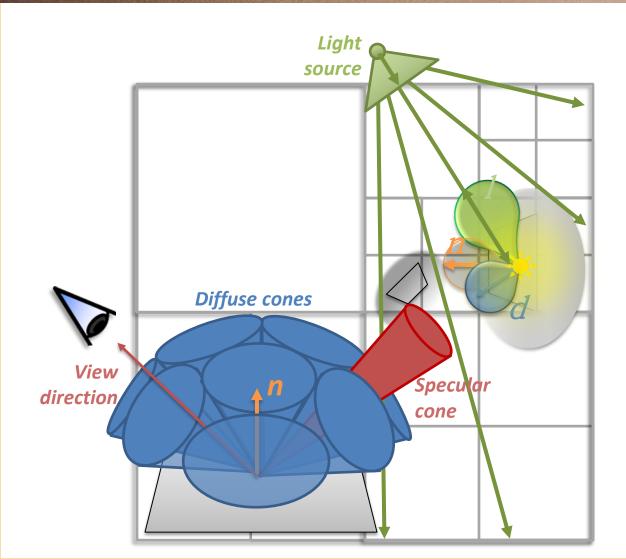
Interactive Indirect Illumination Using Voxel Cone Tracing





Rendering algorithm



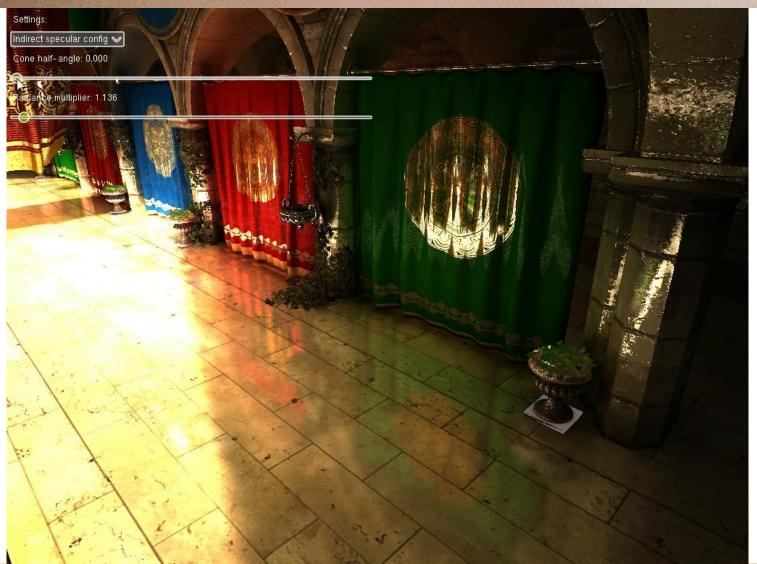


- 1. Light injection
 - Rasterization (RSM)
- 2. Light filtering
 - Compute
- 3. Camera pass (final gathering)
 - Forward FS or deferred compute shader

Importance sampling of the BRDF

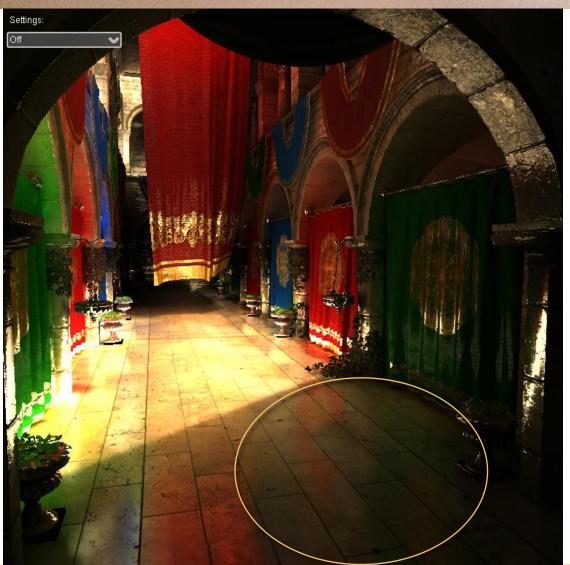
Glossy reflections





Multiple-bounces





Performances and scalability

- Scalable lighting rep. !
 - Independent of geometric complexity
- Control over rendering time
 - Maximum voxel resolution
 (Number of octree levels)
 - Number of cones per pixel / Aperture of the cones: The wider, the faster!
 - > Graceful performance degradation

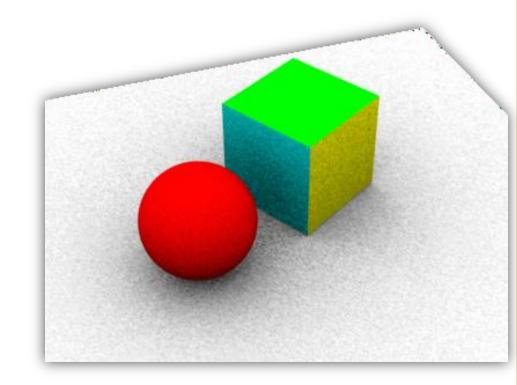


Discussion



- Large cones
 - Precision / Light leaking

But never noisy !!

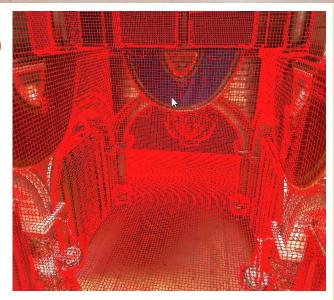


What is the cost of an SVO?



GI Sponza Demo

- Memory consumption:
 - -9 levels SVO: ~200MB-1GB
 - + Temporary buffers for building

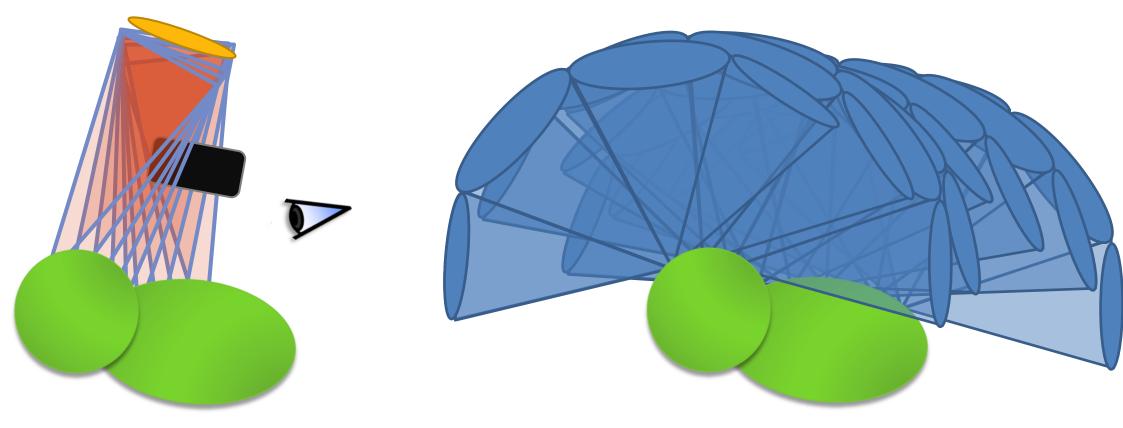


- Construction + Update Time (GK104)
 - Construction : ~70ms at initialization time
 - Update: ~4-5ms / frame

Traversal coherency



Coherency: Execution + Data access



Soft Shadow

Diffuse Tracing

Traversal coherency





Diffuse Only

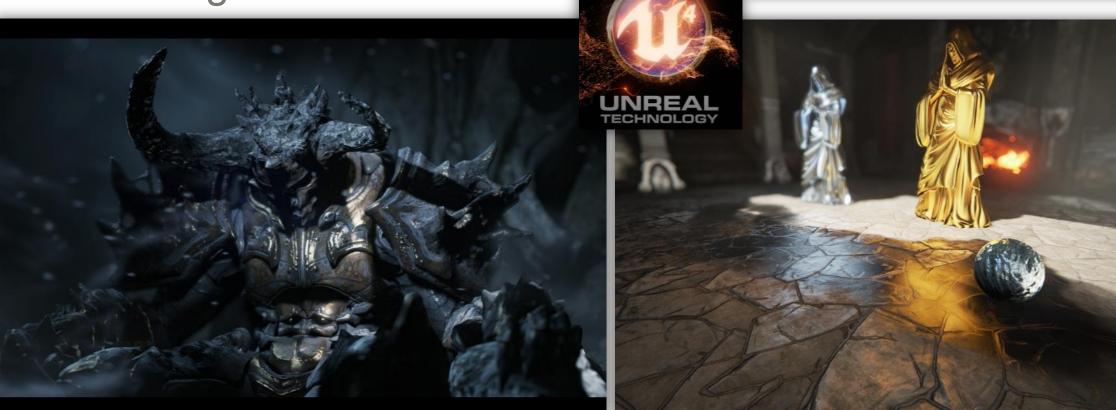


Diffuse + Specular

Voxel-based GI

This can run in a game !

SVOgi





The Technology Behind the "Unreal Engine 4 Elemental Demo"



Martin Mittring

 Advances in Real-Time Rendering in Games: Part II

Wednesday, 8 August 2:05 pm - 3:05 pm

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CONTENT CREATION



Procedural content generation



- Signed Distance Field
 - Procedural generation and Amplification





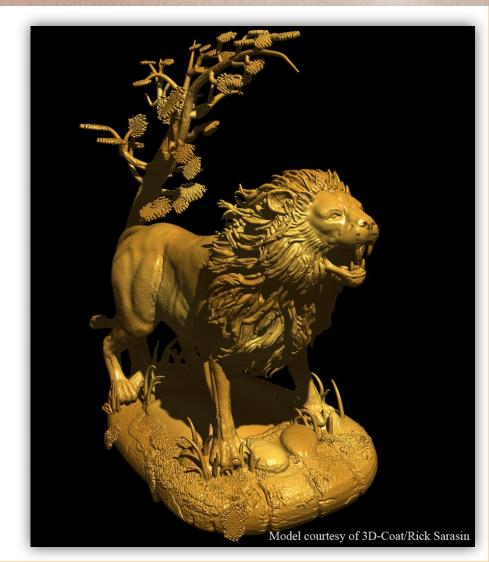
Voxel sculpting



CSG operations

-3D-Coat





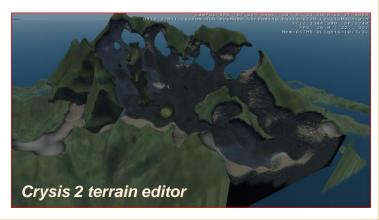
Procedural content generation



LODs

- Eg. Terrain generation in Crysis
- No problem of topology





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OTHER COOL USAGES



World-space light baking



Brick maps

[Christensen and Batali 2004]

- Bake static lighting
- Irradiance volumes

[Greger et al 1998]

- Volume of diffuse lighting samples
- Pre-computed Radiance Transfer
 [Sloan et al. 2002]





Participating medias



- Rendering volumetric effects
 - Smoke, clouds...

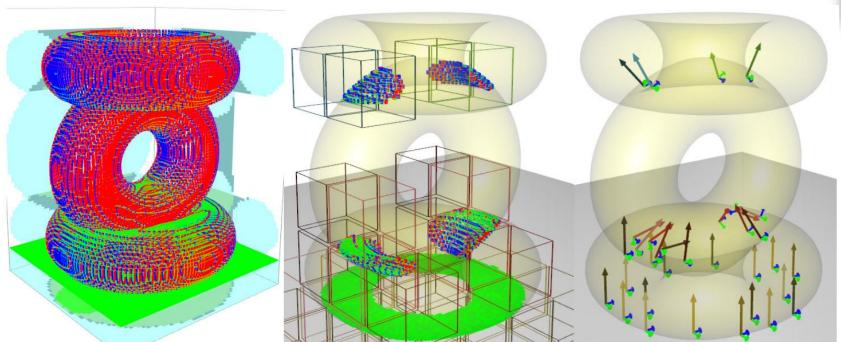


[Greger 98]

Other applications



Physics: Collision detection



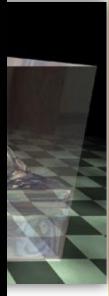


Allard et al. Siggraph 2010









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DISCUSSIONS AND DIRECTIONS



Limitations



Animation and dynamic content

If you use the geometry enough time to amortize,

it is fine!

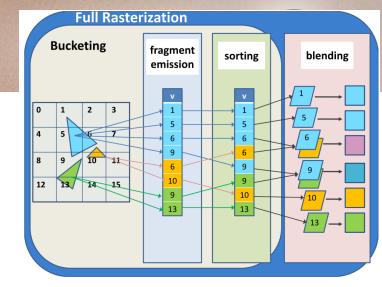


Voxelization

Compute-based

[Schwarz and Seidel 10, Pantaleoni 11]

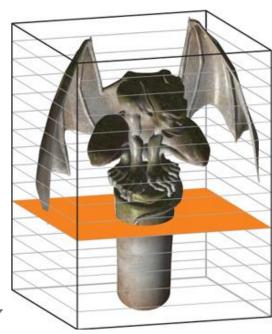
Not using hw rasterizer



VoxelPipe [Pantaleoni 11]

- Multi-pass graphics-based
 - Slice-by-slice / Multiple-slices MRT

[Fang et al. 00, Crane et al. 07, Li et al. 05, Dong et al. 04, Zhang et al. 07, Eisemann and Decoret 08]

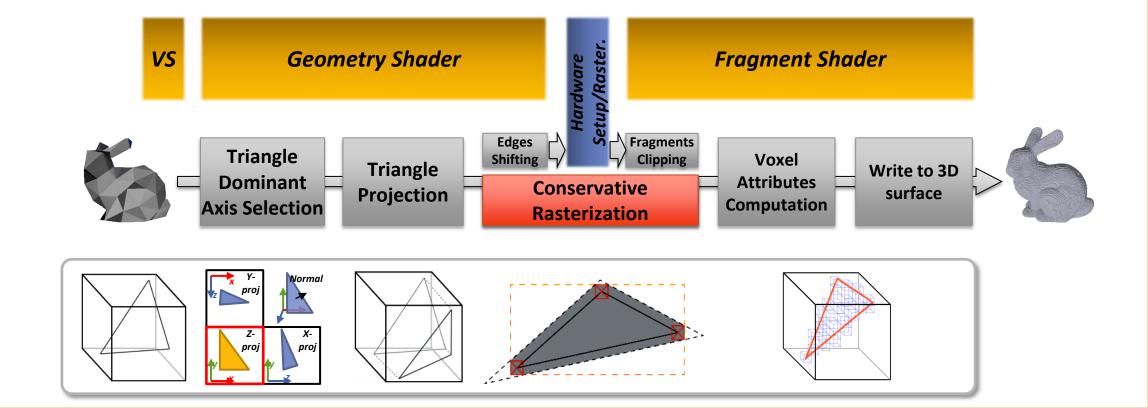


Crane et al. 2007

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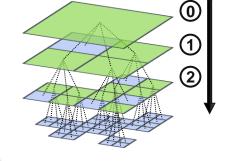
Thin surface / Classical conservative



Octree construction



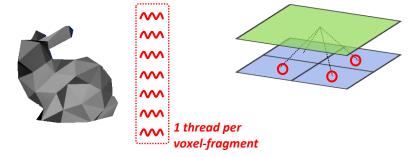
- Top-down octree construction
 - Compute + Graphics

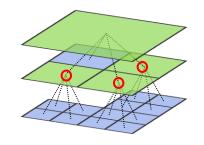


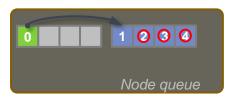


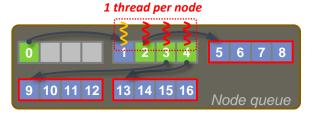


Create New Node Tiles









Performances



- 9 levels octree (512^3)
 - -RGBA32F
- Kepler GK104 performance
 - 30% 58% faster than Fermi GF100



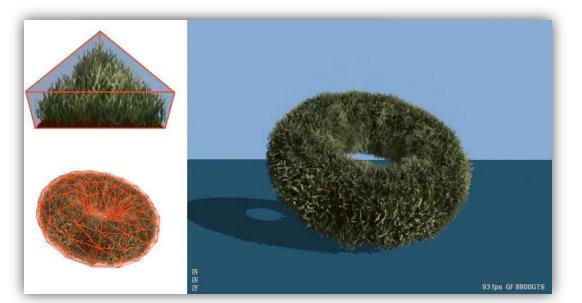
Times in ms	Frag	Octree construction				Write	MIP	Total
Scene	list	Flag	Create	Init	Total	VVIIGE	map	Total
Sponza	2.07	5.65	0.37	1.32	7.34	3.94	2.09	15.44

Voxel deformation

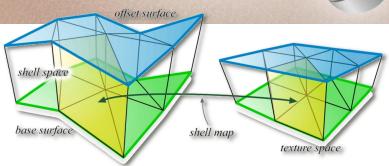
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How to animate large scale of small details?

FFD deformation



[Decaudin and Neyret 2009]



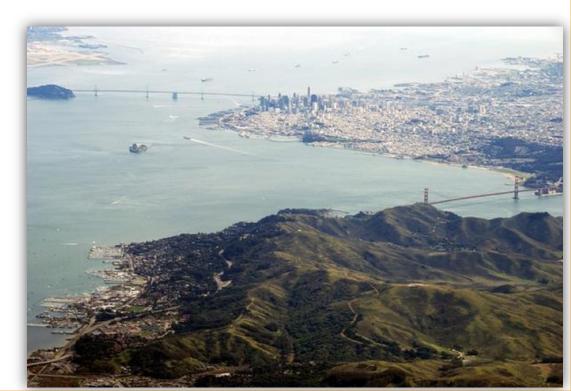
Shell Maps [Porumbescu et al. 05, Jeschke et al. 07]

Composite and animated scene

Limitations



- Memory cost of large scenes
 - Needs streaming or dynamic re-voxelization
 - Well fitted to streaming



Challenges



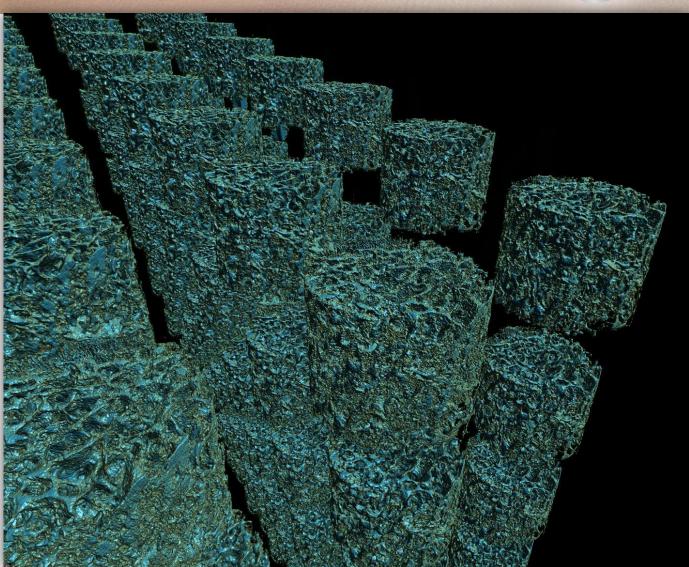
- Problem: Primary rays require massive amounts of voxels!
 - Large scenes + details (screen resolution @ all necessary scales and everywhere)
- Dynamic streaming can be affordable
 - Ideal case: 2/3 voxels per pixel @ 1080p 1920x1080 x3 x32B/voxel ~= 200MB

Massive scenes



8K³ virtual resolution

50ms @512x5128800 GT (2007)~5Mcones/s



Out-of-core



Virtualized virtual memory system Dynamic paging Octree as a hierarchical page-table Virtually unlimited resolution At the cost of a log time point sampling

Acknowledgements



- Johan Andersson
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- David Luebke
- Yury Uralsky
- Ignacio Llamas

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